

# Continuiti: A Generalized Framework for Neural Operators



github.com/aai-institute/continuiti

# WHY NEURAL OPERATORS

# **Direct Mapping Between Function Spaces**

- Enhanced Flexibility: Neural operators map inputs to outputs as functions, offering a flexible framework ideal for problems expressed naturally as functions.
- Reduced Complexity: Avoids the need to discretize function spaces, simplifying model formulation and reducing computational complexity.
- Increased Accuracy: Directly handling functions improves generalization and accuracy.

# **Discretization Independent**

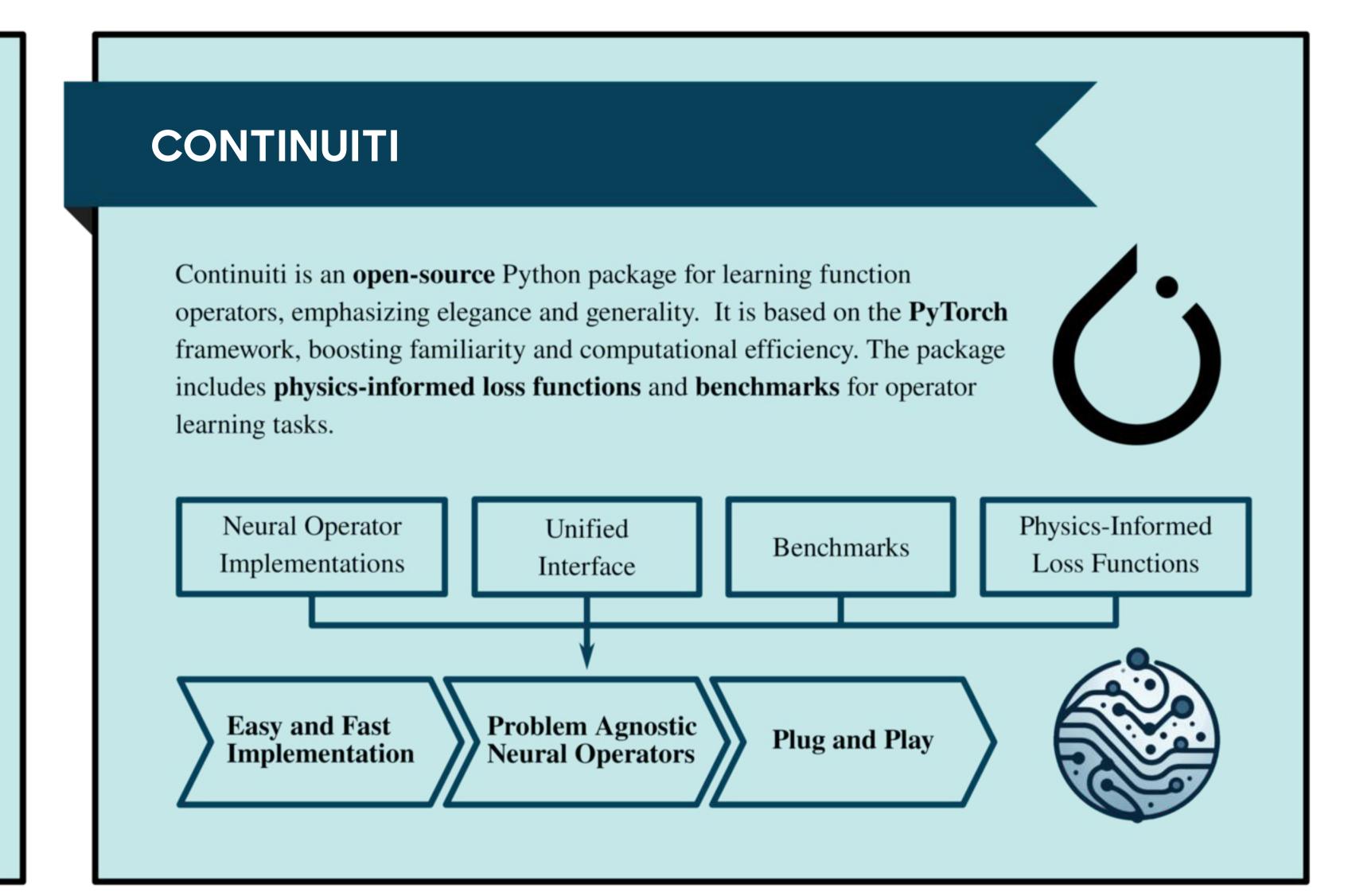
- The discretization of input and output functions can differ between samples.
- Neural operators can evaluate outputs at arbitrarily many points, in any location.

# **Physics Informed**

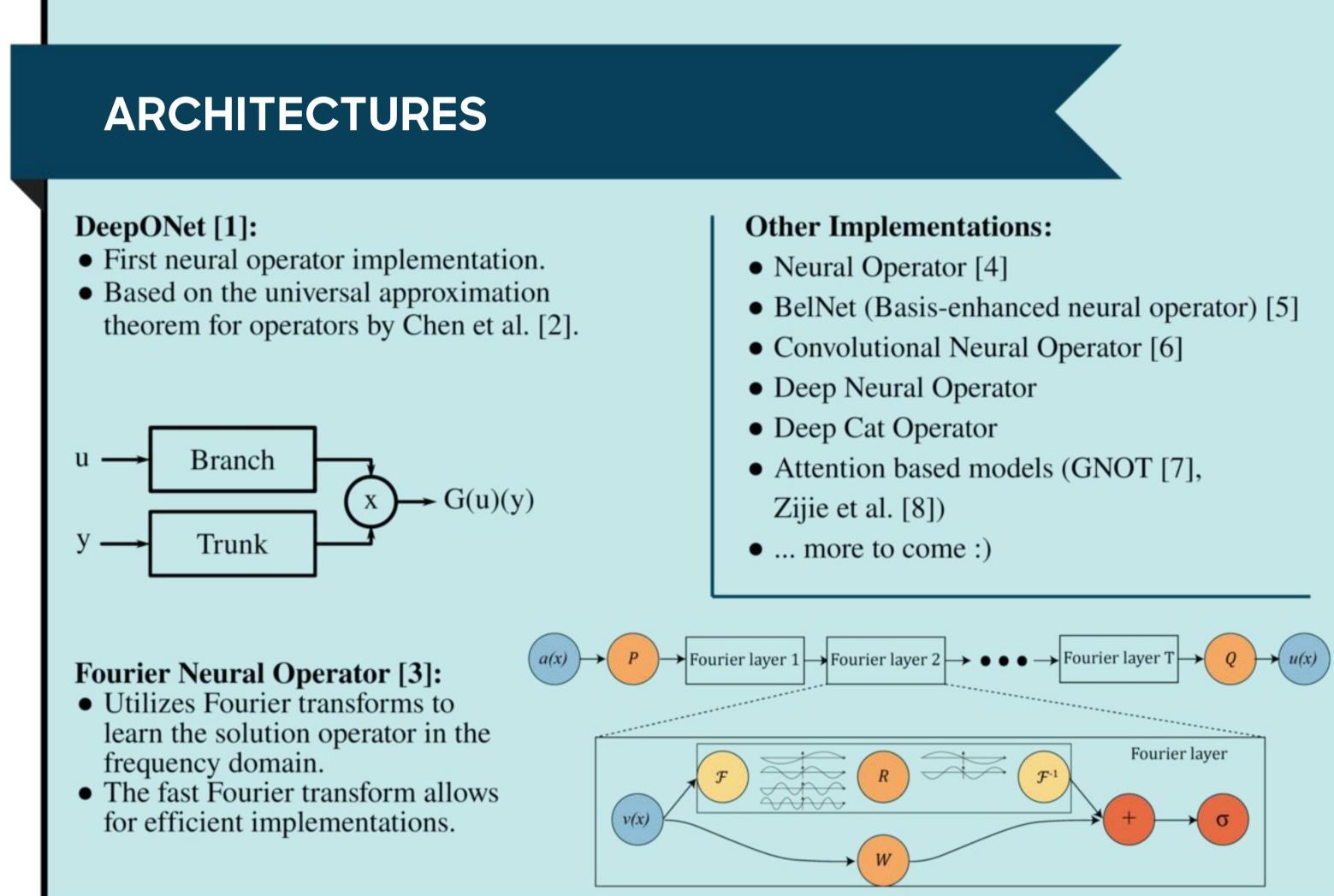
- Seamless integration of physical constraints.
- Partial differential equations are naturally expressed using functions.

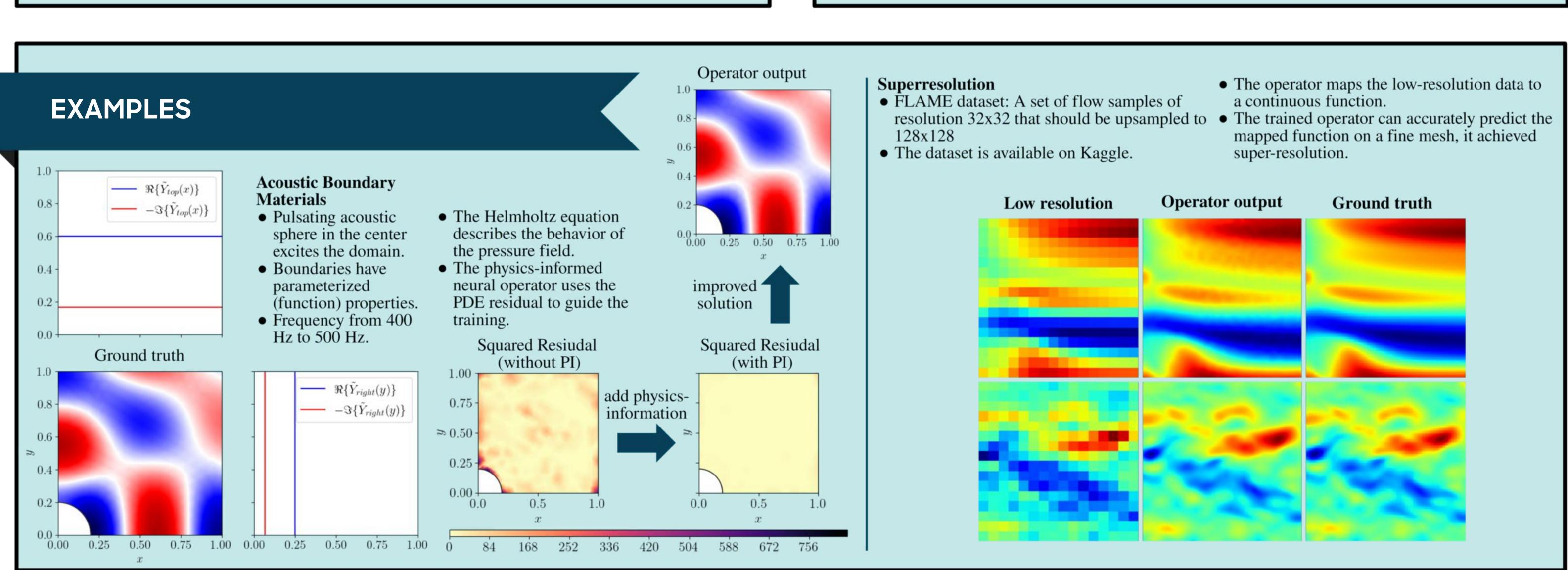
# **Wide Range of Applications**

- Offers high flexibility and faster (even realtime) solutions.
- Provides robust performance across varied problems and datasets.
- Scalable: Effectively handles high-
- dimensional data and complex functions. • Applicable in fields such as fluid dynamics, acoustics, structural mechanics, heat transfer, tomography, plasma physics, material design, seismology, optical systems, and many more.



#### PROBLEM DESCRIPTION Neural operators are designed to learn $\mathcal{A}: X \rightarrow U$ mappings between infinite-dimensional function spaces rather than finitedimensional vector-spaces. **Function** $U: y \rightarrow v$ This approach allows to efficiently Space(s) approximate solutions to partial differential equations and other functional problems. • The resulting output function can be evaluated at arbitrarily many points, providing a flexible and powerful solution to the problem. Vector Space(s) In Continuiti: • The operator mapping is defined with: >>> dno = DeepNeuralOperator() • The problem is described by the mapping: >>> v = dno(x, u, y) $G: \mathcal{A} \rightarrow \mathcal{U}$ • Neural operator implementations can be swapped out seamlessly. • The neural operator approximates the mapping: Straightforward workflow through generalized datasets. $G \approx G_{\theta}$





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